Name:

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## Homework Assignment #6

(Due Date: Monday, October 23, 12:40 pm, in class)

- 6.1 Ideal Wave Equation and Spectral Analysis (cf. Ex. 6.1, 6.9) (8 pts.) Write a FORTRAN program to numerically calculate the signal propagation on an ideal string (length L = 1m, tension force  $F_T = 900N$ , mass density  $\mu = 0.010 kg/m$ ) using the ideal wave equation.
  - (a) Assume one end of the string fixed and the other end open. Impart an initial Gaussian pluck on the string,  $y(x, t_{0,1}) = \exp[(x x_0)^2/2\sigma_x^2]$  with  $x_0$  40% away from the open end, and a full width at half maximum of 0.05m (what is the corresponding value of  $\sigma_x$ ?). Study the signal propagation by plotting time snapshots of your solution,  $y(x, t_s)$ , as the signal moves across the string. How are the signals reflected at the ends?
  - (b) Perform a Fourier analysis of the string excitation in part (a) (i.e., for a fixed position on the string, record y(t) and evaluate the Fourier transform using a suitable time discretization) and plot the power spectrum vs. frequency. Interpret the peaks in the spectrum in terms of the harmonics of the string.
  - (c) Consider now the same string but with both ends fixed. Initialize it with a more realistic "triangular" pluck, with a maximum  $y(L/3, t_{0,1}) = 0.2m$ , which linearly connects to the ends (see Fig. 1 below). Study its time dependence and power spectrum in analogy to parts (a) and (b).

Fig.1: Realistic Pluck

6.2 Stiffness Term in Wave Equation (cf. Ex. 6.15) (2 pts.) The wave equation with stiffness correction for a string under tension  $F_T$  reads

$$\frac{\partial^2 y}{\partial t^2} = c^2 \left( \frac{\partial^2 y}{\partial x^2} - \frac{Y}{F_T} \frac{\partial^4 y}{\partial x^4} \right) , \qquad (1)$$

with Y: Young's modulus (no numerical work required in this problem).

- (a) Derive the symmetric finite difference expression of the 4. order derivative term suitable for numerical evaluation.
- (b) Derive the finite difference expression for y(i, n+1) for the string displacement y at time  $t_{n+1}$  and position  $x_i$  in terms of y at times  $t_{n,n-1}$  and positions  $x_{i-2,i-1,i,i+1,i+2}$ .