PHYS 606 - Spring 2015 - Homework III - Solution

Problem [1]

(a) Induction: eqs (2)+(3) obviously true for
$$n=1$$
; suppose they are true for $n-1$

then $\begin{bmatrix} F_1G^n \end{bmatrix} = G^{n-1}[F_1G] + [F_1G^n]G = G^{n-1}[F_1G] + (n-2)G^{n-2}[F_1G]G$
 $\begin{bmatrix} F^n_1G \end{bmatrix} = F^{n-1}[F_1G] + [F^{n-1}_1G]F = F^{n-1}[F_1G] + (n-2)F^{n-2}[F_1G]F$

Protect rule

$$= \begin{bmatrix} (n-1)G^{n-1}[F_1G] \end{bmatrix}$$

Quest Calculation is also possible.

Problem [2]

$$[\mp_{\rho}(\vec{r}), G_{\rho}(\vec{p})] + (\vec{r}) = (2\pi \hbar)^{-3/2} \int [\mp_{\rho}(\vec{r}), G_{\rho}(i\hbar\nabla_{\rho})] \hat{f}(\vec{p}) e^{\frac{i}{\hbar}\vec{r}\cdot\vec{p}} d^{3}p$$

$$= (2\pi \hbar)^{-3/2} \int (\mp_{\rho}(\vec{p}), \hat{f}(\vec{p}), G_{\rho}(\vec{p})) e^{\frac{i}{\hbar}\vec{r}\cdot\vec{p}} - G_{\rho}(i\hbar\nabla_{\rho}) \hat{f}(\vec{p}), F_{\rho}(i\hbar\nabla_{\rho}) e^{\frac{i}{\hbar}\vec{r}\cdot\vec{p}}) d^{3}p$$

$$= (2\pi \hbar)^{-3/2} \int (G_{\rho}(\vec{p}), \hat{f}(\vec{p}), F_{\rho}(i\hbar\nabla_{\rho})) e^{\frac{i}{\hbar}\vec{r}\cdot\vec{p}} - \hat{f}(\vec{p}), F_{\rho}(i\hbar\nabla_{\rho}), F_{\rho}(i\hbar\nabla_{\rho}) e^{\frac{i}{\hbar}\vec{r}\cdot\vec{p}}) d^{3}p$$

$$= (2\pi \hbar)^{-3/2} \int (F_{\rho}(\vec{p}), \hat{f}(\vec{p}), F_{\rho}(i\hbar\nabla_{\rho})) e^{\frac{i}{\hbar}\vec{r}\cdot\vec{p}} - \hat{f}(\vec{p}), F_{\rho}(i\hbar\nabla_{\rho}), F_{\rho}(i\hbar\nabla_$$

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[3] \frac{d}{dt}\langle p\rangle = \langle F\rangle = 0 (free particle) \Rightarrow \langle p\rangle(t) = \langle p\rangle(0) = const.
(Chrenket)
      \frac{d}{dx}\langle x \rangle = \frac{\langle p \rangle}{dx} = \frac{p_0}{dx}
              \Rightarrow \langle x \rangle(t) = \frac{p_0}{m} t + x_0 \qquad x_0 = \langle x \rangle(0)
           \frac{d}{dt}\langle p^2\rangle = \frac{1}{it}\langle [p,T]\rangle = 0 \Rightarrow \langle p^2\rangle(t) = \langle p^2\rangle(0) = const.
             \Rightarrow (\Delta p)^{2}(t) = \langle (p - \langle p \rangle)^{2} = \langle p^{2} \rangle(t) - (\langle p \rangle(t))^{2} = \langle p^{2} \rangle(0) - p_{0}^{2} = (\Delta p)^{2}(0) = const.
           \frac{d}{dt} \langle x^2 \rangle = \frac{1}{i\hbar} \langle [x^2, \frac{p^2}{2m}] \rangle = \frac{1}{i\hbar} \langle p[x^2, \frac{p}{2m}] + [x^2, \frac{p}{2m}] p \rangle
                           = to px[x,p]+p[x,p]x+x[x,p]p+[x,p]xp) =m
                          = in (px+xp)
            d <px> = it (px, T) = 2T = const. = d (xp)
            > (px+xp)(t) = 2(p2)(0) t + (px+xp)(0)
            \Rightarrow \langle x^2 \rangle = \frac{\langle p^2 \rangle \langle 0 \rangle}{\langle x^2 \rangle} t^2 + \frac{1}{m} \langle p x + x p \rangle \langle 0 \rangle t + \langle x^2 \rangle \langle 0 \rangle
           \Rightarrow (\Delta x)^{2}(t) = \langle x^{2}\rangle(t) - (\langle x\rangle(t))^{2} = \frac{\langle p^{2}\rangle(0) - p_{0}^{2}}{4}t^{2} + \frac{1}{m}(\langle px + xp\rangle(0) - 2x_{0}p_{0})
                                                                                                                           +\langle x^2\rangle(0)-\chi^2
                        = \frac{(\Delta p)^{2}(t)}{4t^{2}} t^{2} + \frac{2}{4t} \left( \frac{i}{2} \langle px + xp \rangle (0) - \langle p \rangle (0) \langle x \rangle (0) \right) t + (\Delta x)^{2} (0)
[4] (a) Gauss: (\Delta x)^2(0) = \sigma^2, (\Delta p)^2(0) = \frac{\hbar^2}{4\sigma^2} (HWI, [3])
                                       (xx)=x0, (p>(0) = the = p0
                     \langle xp \rangle (0) = \frac{1}{\sqrt{2\pi}\sigma} \int e^{-\frac{(x-x)^2}{4\sigma^2}} e^{-\frac{1}{h}p_0x} \times (-i\hbar\frac{d}{dx}) e^{-\frac{(x-x)^2}{4\sigma^2}} e^{+\frac{1}{h}p_0x} dx
                                  = \frac{1}{\sqrt{2\pi\sigma}} \int e^{-\frac{(x-x_0)^2}{2\sigma^2}} \times \left(p_0 + i\hbar \frac{x-x_0}{2\sigma^2}\right) dx
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$$\begin{array}{l} = \frac{1}{12\pi^{2}\sigma} \int e^{-\frac{k^{2}}{2\sigma^{2}}} \left(2\rho_{0} + i\pi \frac{u^{2}}{2\sigma^{2}} + x_{0}\rho_{0} + i\pi x_{0} \frac{u^{2}}{2\sigma^{2}} \right) d \\ = x_{0}\rho_{0} + i\pi \frac{\sigma^{2}}{2\sigma^{2}} = x_{0}\rho_{0} + \frac{1}{2}i\pi \\ \left\langle p_{x} \right\rangle(0) = \text{Since as above + tense with } \left(-i\pi \frac{d}{dx} \right) \text{ acting on } x \\ = x_{0}\rho_{0} + \frac{1}{2}i\pi + \frac{1}{12\pi\sigma} \int e^{-\frac{k^{2}}{2\sigma^{2}}} \left(-i\pi \right) = x_{0}\rho_{0} - \frac{1}{2}i\pi \\ \Rightarrow \frac{1}{2} \left\langle p_{x} + x_{p} \right\rangle(0) = x_{0}\rho_{0} \\ \Rightarrow \left(\Delta x \right)^{2}(t) = \frac{\hbar^{2}}{4\sigma^{2}} t^{2} + \sigma^{2} \quad \text{cucl} \left(\Delta p \right)^{2}(t) = \frac{\pi^{2}}{4\sigma^{2}} \\ \left(b \right) \left(\Delta p \right)^{2}(t) = \frac{\hbar^{2}}{4\sigma^{2}} \int e^{-\frac{\rho_{0}\rho_{0}t}{4\sigma^{2}}} \int e^{-\frac{i\pi(\rho_{0}p_{0}x_{0} - i\omega(\rho)t)^{2}}{2(\rho^{2} + i\pi^{2})^{2}} \int \frac{dp}{dp} \left(\hat{\sigma} = \frac{\pi}{2\sigma} \right) \\ = \left(\Delta p \right)^{2}(0) = \hat{\sigma}^{2} = \frac{\hbar^{2}}{4\sigma^{2}} \\ \left(\Delta p \right)^{2}(t) = \frac{1}{\sqrt{2}\pi^{2}} \int \frac{dp}{dp} \int \frac{dp}{dp} \left(x_{0} + t_{0} + t_{0} + t_{0} + t_{0} + t_{0} + t_{0} + t_{0}}{2(\sigma^{2} + t_{0} + t_{0} + t_{0} + t_{0})^{2}} \right) = x_{0} + t_{0} +$$