

1

PHYS 606 - Spring 2014 - HW V Solution

$$[1] (a) \frac{d}{dt} \langle x \rangle = \frac{1}{i\hbar} \langle [x, H] \rangle = \frac{1}{i\hbar} \langle \frac{i}{m} \hbar p \rangle = \frac{\langle p \rangle}{m}$$

$$\frac{d}{dt} \langle p \rangle = \frac{1}{i\hbar} \langle [p, H] \rangle \stackrel{I.8.2}{=} - \langle \frac{d}{dx} V \rangle = -m\omega^2 \langle x \rangle$$

or directly with Ehrenfest

$$\Rightarrow \frac{d^2}{dt^2} \langle x \rangle = -\omega^2 \langle x \rangle \quad \text{same as for } x_{cl}$$

$$\langle x \rangle(t) = A \cos \omega t + B \sin \omega t; \quad \langle x \rangle(0) = \langle x \rangle_0 \Rightarrow A = \langle x \rangle_0$$

$$\langle p \rangle(0) = m \frac{d\langle x \rangle(0)}{dt} = \langle p \rangle_0 \Rightarrow \omega B = \frac{\langle p \rangle_0}{m}$$

$$\Rightarrow \langle x \rangle(t) = \langle x \rangle_0 \cos \omega t + \frac{\langle p \rangle_0}{m\omega} \sin \omega t$$

$$(b) \frac{d}{dt} \langle T-V \rangle = \frac{1}{i\hbar} \langle [T-V, H] \rangle = \frac{1}{i\hbar} \langle [T, V] - [V, T] \rangle = \frac{2}{i\hbar} \langle \frac{p}{2m} [p, V] + [p, V] \frac{p}{2m} \rangle$$

$\underbrace{\quad}_{-i\hbar \frac{dV}{dx}}$

$$= -\omega^2 \langle px + xp \rangle$$

$$\frac{d}{dt} \langle px + xp \rangle = \frac{1}{i\hbar} \langle [px + xp, H] \rangle \stackrel{I.10}{=} 2 \langle iT - x \underbrace{\frac{dV}{dx}}_{2V} \rangle = 4 \langle T-V \rangle$$

$$\Rightarrow \frac{d^2}{dt^2} \langle T-V \rangle = -4\omega^2 \langle T-V \rangle$$

$$\Rightarrow \langle T-V \rangle(t) = A' \cos 2\omega t + B' \sin 2\omega t; \quad \langle T-V \rangle(0) = A' =: \langle T-V \rangle_0$$

$$\Rightarrow \langle T-V \rangle(t) = (\langle T \rangle_0 - \langle V \rangle_0) \cos 2\omega t - \frac{\omega}{2} \langle px + xp \rangle_0 \sin 2\omega t$$

$\frac{d}{dt} \langle T-V \rangle(0) = 2\omega B' = -\omega^2 \langle px + xp \rangle_0$

$$\text{Now } \langle x^2 \rangle = \frac{2}{m\omega^2} \langle V \rangle = \frac{1}{m\omega^2} \langle H - (T-V) \rangle \stackrel{I}{=} \frac{1}{m\omega^2} (\langle T \rangle_0 + \langle V \rangle_0 - \langle T-V \rangle)$$

$\langle H \rangle = E = \text{const.}$

$$= \frac{1}{m\omega^2} \left(\langle T \rangle_0 \underbrace{(1 - \cos 2\omega t)}_{2\sin^2 \omega t} + \langle V \rangle_0 \underbrace{(1 + \cos 2\omega t)}_{2\cos^2 \omega t} + \frac{\omega}{2} \langle px + xp \rangle_0 \sin 2\omega t \right)$$

$$= \frac{\langle p \rangle_0^2}{m^2 \omega^2} \sin^2 \omega t + \langle x^2 \rangle_0 \cos^2 \omega t + \frac{1}{2m\omega} \langle px + xp \rangle_0 \sin 2\omega t$$

2

$$(c) (\Delta x)^2(t) = \langle x^2 \rangle_t - \langle x \rangle_t^2 = \frac{(\Delta p)_0^2}{m^2 \omega^2} \sin^2 \omega t + (\Delta x)_0^2 \cos^2 \omega t + \frac{1}{2m\omega} (\langle px + xp \rangle_0 - 2\langle x \rangle_0 \langle p \rangle_0) \sin 2\omega t$$

where

$$(\Delta p)_0^2 = \langle p^2 \rangle_0 - \langle p \rangle_0^2; (\Delta x)_0^2 = \langle x^2 \rangle_0 - \langle x \rangle_0^2$$

$$\text{Limit } \omega \rightarrow 0: \cos \omega t \rightarrow 1, \sin \omega t \rightarrow t$$

$$(\Delta x)^2(t) \rightarrow \frac{(\Delta p)_0^2}{m^2} t^2 + (\Delta x)_0^2 + (\langle px + xp \rangle_0 - 2\langle x \rangle_0 \langle p \rangle_0) \frac{t}{m}$$

as in HWK, [3]

$$[2] (a) \frac{\partial \mathcal{L}}{\partial t} = -\frac{d\vec{R}}{dt} \cdot \nabla \delta^{(3)}(\vec{r} - \vec{R}) = -\dot{\vec{R}} \cdot \nabla \delta^{(3)}(\vec{r} - \vec{R})$$

chain rule

$$\nabla_{\vec{r}} \mathcal{L} = \dot{\vec{R}} \cdot \nabla \delta^{(3)}(\vec{r} - \vec{R})$$

$$\Rightarrow \frac{\partial \mathcal{L}}{\partial t} + \nabla_{\vec{r}} \mathcal{L} = 0$$

recall: \vec{r}, \vec{R} are indep. quantities to describe a system in cl. mechanics

$$(b) \langle \rho \rangle = \int \psi^*(\vec{r}) \delta^{(3)}(\vec{r} - \vec{R}) \psi(\vec{r}) d^3r = \psi^*(\vec{R}) \psi(\vec{R}) = \rho_{\text{Schr.}}(\vec{R})$$

probability density of the Schrödinger field

$$\langle \vec{j} \rangle = \frac{1}{2m} \int \psi^*(\vec{r}) (-i\hbar \nabla_r \delta^{(3)}(\vec{r} - \vec{R}) + \delta^{(3)}(\vec{r} - \vec{R}) (-i\hbar \nabla_r)) \psi(\vec{r}) d^3r$$

$$= \frac{i\hbar}{2m} \left[\int (\nabla_r \psi)^*(\vec{r}) \delta^{(3)}(\vec{r} - \vec{R}) \psi(\vec{r}) d^3r - \int \psi^*(\vec{r}) \delta^{(3)}(\vec{r} - \vec{R}) (\nabla_r \psi)(\vec{r}) d^3r \right]$$

$$= \frac{i\hbar}{2m} \left[\nabla \psi^*(\vec{R}) \psi(\vec{R}) - \psi^*(\vec{R}) \nabla \psi(\vec{R}) \right] = \vec{j}_{\text{Schr.}}(\vec{R})$$

current for the Schrödinger field probability density

$$[3] (a) \text{ Hamilton-Jacobi: } \frac{\partial S}{\partial t} + \frac{1}{2m} (\nabla S - q\vec{A})^2 + q\phi = 0$$

with $\vec{p} = \nabla S$

$$\text{Continuity eqn.: } \frac{\partial \rho}{\partial t} + (\nabla \cdot \vec{j}) \rho + \vec{j} \cdot \nabla \rho = 0 \Rightarrow \frac{\partial \rho}{\partial t} + \frac{q}{m} \nabla \cdot (\vec{p} - q\vec{A}) + \frac{1}{m} \nabla \rho \cdot (\vec{p} - q\vec{A}) = 0$$

(I.5.3)

(b) Ansatz $\psi(\vec{r}, t) = C e^{\frac{i}{\hbar} S}$ with C, S real into

$$i\hbar \frac{\partial \psi}{\partial t} = \frac{1}{2m} (-i\hbar \nabla - q\vec{A})^2 \psi + q\phi \psi$$

$$\Rightarrow \left(i\hbar \frac{1}{c} \frac{\partial C}{\partial t} - \frac{\partial S}{\partial t} \right) \psi = \frac{1}{2m} \left(-\hbar^2 \frac{\Delta C}{C} + (\nabla S)^2 - i\hbar \Delta S - i\hbar \frac{2}{c} \nabla C \cdot \nabla S + q^2 A^2 + i\hbar \frac{2}{c} q\vec{A} \cdot \nabla C - 2q\vec{A} \cdot \nabla S + i\hbar q \nabla \cdot \vec{A} \right) \psi + q\phi \psi$$

Drop ψ from eq. and separate imaginary and real part:

$$\text{Re: } 0 = \frac{\partial S}{\partial t} + \frac{1}{2m} \left((\nabla S)^2 - \hbar^2 \frac{\Delta C}{C} - 2 \nabla S \cdot (q\vec{A}) + (q\vec{A})^2 \right) + q\phi$$

0 for $\hbar \rightarrow 0$

$$\Rightarrow 0 = \frac{\partial S}{\partial t} + \frac{1}{2m} (\nabla S - q\vec{A})^2 + q\phi \quad \text{Hamilton-Jacobi!}$$

$$\text{Im: } \frac{2C}{\partial t} \frac{\partial C}{\partial t} = \frac{1}{2m} \left(-2C^2 \Delta S - 4C \nabla C \cdot \nabla S + 4C (\nabla C) \cdot (q\vec{A}) + 2C^2 q \nabla \cdot \vec{A} \right)$$

$\frac{\partial S}{\partial t}$ S $\nabla \vec{p}$ $2 \nabla S$ \vec{p} $2 \nabla S$ S

where $S = C^2 = |\psi|^2$; $\Rightarrow \frac{\partial S}{\partial t} + \frac{1}{m} \nabla \cdot (\vec{p} - q\vec{A}) + \frac{1}{m} \nabla S \cdot (\vec{p} - q\vec{A}) = 0$

continuity equation.

[4] Define $\vec{A}' = \vec{A} + \nabla f$; $\phi' = \phi - \frac{\partial f}{\partial t}$; $\psi' = \psi e^{\frac{i}{\hbar} qf}$

Proof of invariance in two parts.

$$i) \quad i\hbar \frac{\partial \psi'}{\partial t} - q\phi' \psi' = \left(i\hbar \frac{\partial \psi}{\partial t} \right) e^{\frac{i}{\hbar} qf} + \left(-q \frac{\partial f}{\partial t} \right) \psi e^{\frac{i}{\hbar} qf} - q\phi \psi e^{\frac{i}{\hbar} qf} + q \frac{\partial f}{\partial t} \psi e^{\frac{i}{\hbar} qf}$$

$$= \left(i\hbar \frac{\partial \psi}{\partial t} - q\phi \psi \right) e^{\frac{i}{\hbar} qf}$$

$$ii) \quad (-i\hbar \nabla - q\vec{A})^2 \psi' = (-i\hbar \nabla - q\vec{A})^2 \psi e^{\frac{i}{\hbar} qf} + q^2 (\nabla f)^2 \psi e^{\frac{i}{\hbar} qf} + (-i\hbar \nabla - q\vec{A}) \cdot (-q \nabla f) \psi e^{\frac{i}{\hbar} qf}$$

$$+ (-q \nabla f) \cdot (-i\hbar \nabla - q\vec{A}) \psi e^{\frac{i}{\hbar} qf}$$

$$= \left[(-i\hbar \nabla - q\vec{A})^2 \psi \right] e^{\frac{i}{\hbar} qf} + \underbrace{2 \left[(-i\hbar \nabla - q\vec{A}) \psi \right] (-i\hbar \nabla)}_{q \nabla f e^{\frac{i}{\hbar} qf}} e^{\frac{i}{\hbar} qf} + \underbrace{\left[(-i\hbar \nabla)^2 \psi \right] e^{\frac{i}{\hbar} qf}}_{q^2 (\nabla f)^2 e^{\frac{i}{\hbar} qf} - i\hbar q \Delta f e^{\frac{i}{\hbar} qf}} \psi$$

$$+ q^2 (\nabla f)^2 \psi e^{\frac{i}{\hbar} qf} + i\hbar q \Delta f \psi e^{\frac{i}{\hbar} qf} - 2q^2 (\nabla f)^2 \psi e^{\frac{i}{\hbar} qf} - \left[2q \nabla f \cdot (-i\hbar \nabla - q\vec{A}) \psi \right] e^{\frac{i}{\hbar} qf}$$

(4)

$$= \left[(-i\hbar \nabla - q\vec{A})^2 \psi \right] e^{\frac{i}{\hbar} q\phi}$$

$$\Rightarrow \text{the transformed S.E. } i\hbar \frac{\partial \psi'}{\partial t} = \frac{1}{2m} (-i\hbar \nabla - q\vec{A}')^2 \psi' + q\phi' \psi'$$

is identical to the original equation times an overall phase factor which can be dropped.

$$\begin{aligned} \text{(b)} \quad m \frac{d}{dt} \langle v_k \rangle &= \frac{1}{i\hbar} \left\langle \left[p_k - qA_k, \frac{(\vec{p} - q\vec{A})^2}{2m} + q\phi \right] \right\rangle + m \left\langle \frac{\partial v_k}{\partial t} \right\rangle \quad k=1,2,3 \\ &= \frac{1}{i\hbar} \left\langle (p_k - qA_k) [p_k - qA_k, p_k - qA_k] \frac{1}{2m} + [p_k - qA_k, p_k - qA_k] (p_k - qA_k) \frac{1}{2m} \right\rangle \\ &\quad - q \left\langle \frac{\partial v_k}{\partial t} \phi \right\rangle - q \left\langle \frac{\partial A_k}{\partial t} \right\rangle \quad \underbrace{i\hbar q \left(\frac{\partial A_k}{\partial x_k} - \frac{\partial A_k}{\partial x_k} \right)} \\ &= q \langle E_k \rangle \end{aligned}$$

$$= q \langle E_k \rangle + \frac{q}{2} \left\langle v_l \left(\frac{\partial A_l}{\partial x_k} - \frac{\partial A_k}{\partial x_l} \right) + \left(\frac{\partial A_l}{\partial x_k} - \frac{\partial A_k}{\partial x_l} \right) v_l \right\rangle$$

$$\text{on the other hand } [\vec{v} \times (\nabla \times \vec{A})]_k = \epsilon_{k\ell m} v_\ell \epsilon_{mno} \frac{\partial}{\partial x^n} A_o$$

$$= (\delta_{kn} \delta_{\ell o} - \delta_{ko} \delta_{\ell n}) v_\ell \frac{\partial}{\partial x^n} A_o = v_\ell \left(\frac{\partial}{\partial x_k} A_\ell - \frac{\partial}{\partial x_\ell} A_k \right)$$

$$\Rightarrow m \frac{d}{dt} \langle \vec{v} \rangle = q \langle \vec{E} \rangle + \frac{q}{2} \langle \vec{v} \times \vec{B} + \vec{B} \times \vec{v} \rangle$$